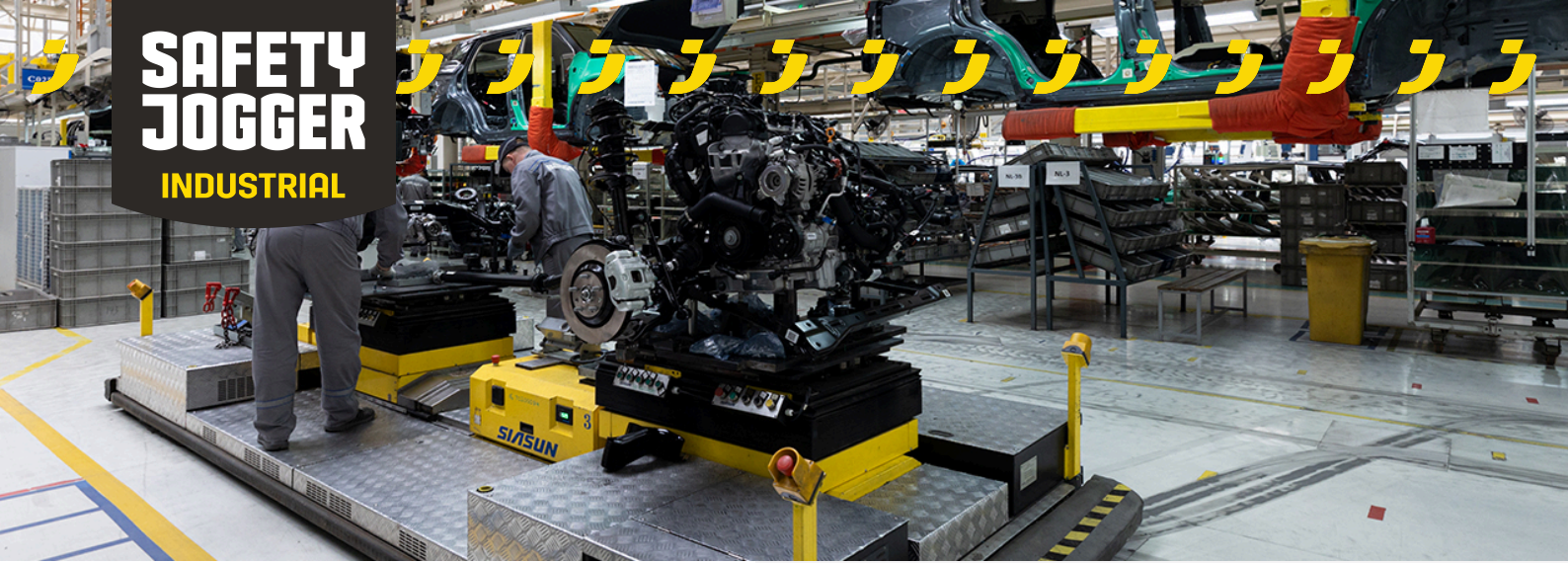


SAFETY JOGGER

INDUSTRIAL



ALLFLEX 4131A

Maximum dexterity and sensitivity safety gloves for the most delicate handling

The seamless ALLFLEX gloves of Safety Jogger are designed for light and delicate applications for which a maximum of agility and sensitivity are an absolute must. Excellent for delicate assembly and other light handling. Nylon spandex liner with black micro foam nitrile coating for precision handling in dry conditions.

Performance level	4131A
Liner	Nylon + spandex
Coating	PU + nitrile microfoam
Size range	EU 6-12
Norms	EN 420:2016 EN 388:2016



EN ISO 420

EN 388:2016



Industries:

Assembly, Automotive, Chemical, Cleaning, Construction, Logistics, Mining, Oil & Gas, Industry, Tactical



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Performance level 4131A

EN388:2016	0	1	2	3	4	5
a. Abrasion resistance (cycles)	< 100	100	500	2000	8000	-
b. Cut resistance (factor)	< 1.2	1.2	2.5	5.0	10.0	20.0
c. Tear resistance (newton)	< 10	10	25	50	75	-
d. Puncture resistance (newton)	< 20	20	60	100	150	-

EN ISO 13997 (TDM-100 test)	A	B	C	D	E	F
e. Straight blade cut resistance (newton)	2	5	10	15	22	30

- Abrasion resistance: based on the number of cycles required to rub through the sample glove.
- Cut resistance: based on the number of cycles required to cut through the sample at a constant speed with a rotating blade.
- Tear resistance: based on the amount of force required to tear the sample.
- Puncture resistance: based on the amount of force required to pierce the sample with a standard sized point.
- Cut resistance according TDM100 test based on the number of cycles required to cut through the sample at a constant speed with a sliding blade.